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Linear systems: a measurement based approach to analysis, synthesis and design. In: 3rd IASTED Asian conference on modelling, identification and control

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Linear Systems - A Measurement Based Approach | Shankar P ...

Linear systems: a measurement based approach . By S P Bhattacharyya, L H Keel and D N Mohsenizadeh. Cite . BibTex; Full citation; Abstract. This brief presents recent results obtained on the analysis, synthesis and design of systems described by linear equations. It is well known that linear equations arise in most branches of science and ...

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Linear Measuring System - Measurement In Millimeters ...

In systems theory, a linear system is a mathematical model of a system based on the use of a linear operator. Linear systems typically exhibit features and properties that are much simpler than the nonlinear case. As a mathematical abstraction or idealization, linear systems find important applications in automatic control theory, signal processing, and telecommunications. For example, the propagation medium for wireless communication systems can often be modeled by linear systems.

Linear system - Wikipedia

A system of measurement is a collection of units of measurement and rules relating them to each other. Systems of measurement have historically been important, regulated and defined for the purposes of science and commerce. Systems of measurement in use include the International System of Units, the modern form of the metric system, the British imperial system, and the United States customary system.

System of measurement - Wikipedia

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S. P. P. Bhattacharyya, L.H. Keel, D.N. 100, "Linear Systems: A Measurement Based Approach" English | ISBN: 8132216407 | 2013 | EPUB | 100 pages | 2 MB

This brief presents recent results obtained on the analysis, synthesis and design of systems described by linear equations. It is well known that linear equations arise in most branches of science and engineering as well as social, biological and economic systems. The novelty of this approach is that no models of the system are assumed to be available, nor are they required. Instead, a few measurements made on the system can be processed strategically to directly extract design values that meet specifications without constructing a model of the system, implicitly or explicitly. These new concepts are illustrated by applying them to linear DC and AC circuits, mechanical, civil and hydraulic systems, signal flow block diagrams and control systems. These applications are preliminary and suggest many open problems. The results presented in this brief are the latest effort in this direction and the authors hope these will lead to attractive alternatives to model-based design of engineering and other systems.

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This monograph couples output regulation with several recent developments in modern control theory. It re-examines output regulation theory to achieve a design of controllers that take into account the physical limiting characteristics of actuators such as saturation. The book provides a solution to the basic problem of finding a controller that achieves internal stabilization, results in a desired performance norm, and renders asymptotic tracking of a reference signal even in the presence of persistent disturbances.

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This book introduces electric circuits with variable loads and voltage regulators. It allows to define invariant relationships for various parameters of regime and circuit sections and to prove the concepts characterizing these circuits. Generalized equivalent circuits are introduced. Projective geometry is used for the interpretation of changes of operating regime parameters. Expressions of normalized regime parameters and their changes are presented. Convenient formulas for the calculation of currents are given. Parallel voltage sources and the cascade connection of multi-port networks are described. The two-value voltage regulation characteristics of loads with limited power of voltage source is considered. The book presents the fundamentals of electric circuits and develops circuit theorems. It is useful to engineers, researchers and graduate students who are interested in the basic electric circuit theory and the regulation and monitoring of power supply systems.

This monograph provides an in-depth treatment of the class of linear-dynamical quantum systems. The monograph presents a detailed account of the mathematical modeling of these systems using linear algebra and quantum stochastic calculus as the main tools for a treatment that emphasizes a system-theoretic point of view and the control-theoretic formulations of quantum versions of familiar problems from the classical (non-quantum) setting, including estimation and filtering, realization theory, and feedback control. Both measurement-based feedback control (i.e., feedback control by a classical system involving a continuous-time measurement process) and coherent feedback control (i.e., feedback control by another quantum system without the intervention of any measurements in the feedback loop) are treated. Researchers and graduates studying systems and control theory, quantum probability and stochastics or stochastic control whether from backgrounds in mechanical or electrical engineering or applied mathematics will find this book to be a valuable treatment of the control of an important class of quantum systems. The material presented here will also interest physicists working in optics, quantum optics, quantum information theory and other quantum-physical disciplines.

This thesis makes some theoretical contributions towards mixed quantum feedback network synthesis, quantum optical realization of classical linear stochastic systems and quantum feedback control designs. A mixed quantum-classical feedback network is an interconnected system consisting of a quantum system and a classical system connected by interfaces that convert quantum signals to classical signal (using homodyne detectors), and vice versa (using electro-optic modulators). In the area of mixed quantum-classical feedback networks, we present a network synthesis theory, which provides a natural framework for analysis and design for mixed linear systems. Physical realizability conditions are derived for linear stochastic differential equations to ensure that mixed systems can correspond to physical systems. The mixed network synthesis theory developed based on physical realizability conditions shows that how a classical of mixed quantum-classical systems described by linear stochastic differential equations can be built as a interconnection of linear quantum systems and linear classical systems using quantum optical devices as well as electrical and electric devices. However, an important practical problem for the implementation of mixed quantum-classical systems is the relatively slow speed of classical parts implemented with standard electrical and electronic devices, since a mixed system will not work correctly unless the electronic processing of classical devices is fast enough. Therefore, another interesting work is to show how classical linear stochastic systems build using electrical and electric devices can be physically implemented using quantum optical components. A complete procedure is proposed for a stable quantum linear stochastic system realizing a given stable classical linear stochastic system. The thesis explains how it may be

possible to realize certain measurement feedback loops fully at the quantum level. In the area of quantum feedback control design, two numerical procedures based on extended linear matrix inequality (LMI) approach are proposed to design a coherent quantum controller in this thesis. The extended synthesis linear matrix inequalities are, in addition to new analysis tools, less conservative in comparison to the conventional counterparts since the optimization variables related to the system parameters in extended LMIs are independent of the symmetric Lyapunov matrix. These features may be useful in the optimal design of quantum optical networks. Time delays are frequently encountered in linear quantum feedback control systems such as long transmission lines between quantum plants and linear controllers, which may have an effect on the performance of closed-loop plant controller systems. Therefore, this thesis investigates the problem of linear quantum measurement-based feedback control systems subject to feedback-loop time delay described by linear stochastic differential equations. Several numerical procedures are proposed to design classical controllers that make quantum measurement-based feedback control systems with time delay stable and also guarantee that their desired control performance specifications are satisfied.

Highlighting the Hamiltonian approach to singularly perturbed linear optimal control systems, this volume develops parallel algorithms in independent slow and fast time scales to solve various optimal linear control and filtering problems.

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